

MLFB-Ordering data

6SL3210-1KE21-3UF1



Client order no. :	Item no. :
Order no. :	Consignment no. :
Offer no. :	Project :
Remarks:	

Rated da	ata		
Input			Powe
Number of phases	3 AC		Offse
Line voltage	380 480 \	/ +10 % -20 %	Effic
Line frequency	47 63 Hz		Soun
Rated current (LO)	16.50 A		Powe
Rated current (HO)	12.80 A		Filte
Output			
Number of phases	3 AC		
Rated voltage	400V IEC	480V NEC	Cooli
Rated power (LO)	5.50 kW	7.50 hp	
Rated power (HO)	4.00 kW	5.00 hp	Cool
Rated current (LO)	12.50 A		Insta
Rated current (HO)	8.80 A		Ambie
Rated current (IN)	13.00 A		Oper
Max. output current	17.60 A		Tran
Pulse frequency	4 kHz		Stora
			Relati
Output frequency for vector control	0 240 Hz		Max.
Output frequency for V/f control	0 550 Hz		iviax
Output frequency for V/f control	0 550 Hz		

Rated current (IN)	13.00 A
Max. output current	17.60 A
Pulse frequency	4 kHz
Output frequency for vector control	0 240 Hz
Output frequency for V/f control	0 550 Hz

Overload capability	
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Low	Over	load	Œ	വ

150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time

High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

General tech. specifications			
Power factor λ	0.70 0.85		
Offset factor cos φ	0.95		
Efficiency η	0.97		
Sound pressure level (1m)	63 dB		
Power loss	0.18 kW		
Filter class (integrated)	Unfiltered		

Ambient conditions				
Cooling	Air cooling using an integrated fan			
Cooling air requirement	0.009 m³/s (0.318 ft³/s)			
Installation altitude	1000 m (3280.84 ft)			
Ambient temperature				
Operation	-10 40 °C (14 104 °F)			
Transport	-40 70 °C (-40 158 °F)			
Storage	-40 70 °C (-40 158 °F)			
Relative humidity				

95 % At 40 °C (104 °F), condensation operation and icing not permissible

Closed-loop control techniques			
V/f linear / square-law / parameterizable	Yes		
V/f with flux current control (FCC)	Yes		
V/f ECO linear / square-law	Yes		
Sensorless vector control	Yes		
Vector control, with sensor	No		
Encoderless torque control	No		
Torque control, with encoder	No		



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Mechanical	data	Co	mmunicatio
Degree of protection	IP20 / UL open type	Communication	PROFINET, E
Size	FSB	Connections	
Net weight	2.30 kg (5.07 lb)	Signal cable	
Width	100 mm (3.94 in)	Conductor cross-section	0.15 1.50
Height	196 mm (7.72 in)	Line side	
Depth	208 mm (8.19 in)	Version	Plug-in screv
Inputs / out	puts	Conductor cross-section	4.00 6.00
andard digital inputs		Motor end	
Number	6	Version	Plug-in screv
Switching level: 0→1	11 V	Conductor cross-section	4.00 6.00
witching level: 1→0	5 V	DC link (for braking resisto	or)
Max. inrush current	15 mA	Version	Plug-in screv
il-safe digital inputs		Conductor cross-section	4.00 6.00
umber	1	Line length, max.	15 m (49.21
igital outputs		PE connection	On housing
Number as relay changeover contact	1	Max. motor cable length	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.0
Number as transistor	1	Unshielded	150 m (492.
Output (resistive load)	DC 30 V, 0.5 A		Standards
alog / digital inputs		Compliance with standards	UL, cUL, CE,
umber	1 (Differential input)		
esolution	10 bit	CE marking	EMC Directive 200
witching threshold as digital inp	out		
0→1	4 V		

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Analog outputs

1 → 0

Number 1 (Non-isolated output)

PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy $\pm 5~^\circ\text{C}$

1.6 V



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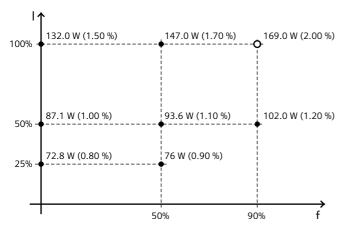
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Figure similar

Converter losses to IEC61800-9-2*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	33.40 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

*converted values